## Pre-Calculus and Trigonometry Capacity Matrix

| Purpose and Vision |  | Understanding and Applying Pre-Calculus and Trigonometry |  | $\begin{aligned} & \stackrel{9}{\mathbf{o g}} \\ & \frac{0}{0} \\ & \frac{0}{3} \\ & \underline{0} \\ & \underline{c} \end{aligned}$ |  | E <br> O <br> ¢ <br> 3 | $\begin{aligned} & \text { O응 } \\ & \text { 윤 } \\ & 0 \end{aligned}$ |
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| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Review Polynomials | A1.1.4 | Add, subtract, multiply and simplify polynomials and rational expressions | X |  |  |  |  |
|  | A1.2.5 | Solve polynomial equations and equations involving rational expressions | X |  |  |  |  |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Review Chapter 1 | Sec 1.5 | Use interval notation | X | X |  |  | Piecewise |
|  | Sec 1.5 | Solve and use properties of inequalities | X |  |  |  |  |
|  | Sec 1.6 | Solve equations involving Absolute Value | X |  |  |  |  |
|  | Sec 1.6 | Solve Inequalities involving Absolute Value | X | X |  |  | Piecewise |
|  | Sec 1.7 | Verbal descriptions into mathematical expressions | X |  |  |  |  |
|  | Sec 1.7 | Solve interest problems, uniform motion problems, mixture problems and constant rate job problems | X |  |  |  |  |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Functions and their Graphs <br> Chapter 3 | P1.1 | Know and use a definition of a function to decide if a given relation is a function | X | X |  |  | Piecewise |
|  | P1.2 | Perform algebraic operations (including compositions) on functions and apply transformations(translations, reflections and rescaling) | X | X |  |  | Shot in the Dark |
|  | P1.6 | Identify and describe discontinuities of a function(greatest integer function) and how these relate to the graph | X |  |  |  |  |
|  | P5.3 | Know and apply the definition and geometric interpretation of the difference quotient | X |  |  |  |  |
|  | P5.3 | Simplify difference quotients and interpret them as rates of change and slopes of secant lines | X |  |  |  |  |
|  | Sec 3.6 | Translate written description of a real world problem into a mathematical model | X |  |  |  |  |
|  | Sec 3.6 | Assign independent and dependent variables Be able to find minimum or maximum value in a real world problem | X | X |  |  | Piecewise |

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| Purpose and Vision |  | Understanding and Applying Pre-Calculus and Trigonometry |  | $\begin{aligned} & \stackrel{0}{80} \\ & \frac{0}{0} \\ & \frac{0}{3} \\ & 0 \\ & \underline{E} \end{aligned}$ |  | $E$ 0 0 0 3 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Function and their Graphs |  | Demonstrate an understanding of relations and functions. Identify the domain, range, dependent and independent variable of the function | X | X |  |  | Piecewise |
| Chapter 3 |  | Translate between different representations of fucntions and relations: graphs, equations, pointsets and tabular. | X |  |  |  |  |
|  |  | Given algebraic, numeric and graphical representations, recongnize functions as polynomial, rational, logarithmic, or exponential. | $\times$ | $\times$ |  |  |  |
|  |  | Identify maximum and minimum values of a a functions in simple situations. Apply solutions of problems. | X | X |  |  |  |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Quadratic functions Chapter4 | P3.2 | Apply quadratic functions and their graphs in the context of motion under gravity and simple optimization problems | X |  |  |  | Shot in the Dark |
|  | P3.3 | Find a quadratic function to model a given datre set or situation | X |  |  |  | Shot in the Dark |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Polynomials and Rational Functions Chapter 5 | P4.1 | Given a polynomial function whose roots are known or can be calculated, find the intervals on which the function's values are positive and negative. |  |  |  |  |  |
|  | P4.2 | Solve Polynomial equations and inequalities of degree greater thatn or equal to three. |  |  |  |  |  |
|  | P4.2 | Graph polynomial functions given in factored form using zeros and their multiplicities, testing the sign-on intervals and analyzing the functions large scalebehavior. |  |  |  |  |  |
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| Purpose and Vision |  | Understanding and Applying Pre-Calculus and Trigonometry |  |  | $\begin{array}{ll} \sum_{3}^{3} & 3 \\ 0 \\ \underline{E} & 0 \end{array}$ | E <br> 0 <br> 0 <br> 3 <br> 3 | O <br> 0 <br>  <br>  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Polynomial and Rational Functions Chapter 5 | P4.3 | Know and apply fundamental facts about polynomials: the Remainder Theorem, the Factor Theorem and the Fundamental Theorem of Algebra. |  |  |  |  |  |
|  | P5.1 | Graph rational functions given in factored form using zeros, identifying asymptotes, analyzing their behaviors for large values of x and testing intervals. |  |  |  |  |  |
|  | P5.2 | Given vertical and horizontal asymptotes, find an exopression for a rational function with these features. |  |  |  |  |  |
| Exponential and Logarithmic Functions Chapter 6 | P2.1 | Use the inverse relationship between exponential and logarithmic functions to solve equations and problems. | X |  |  |  |  |
|  | P2.2 | Graph logarithmic functions. Graph translations and reflections of these functions |  |  |  |  |  |
|  | P2.3 | Solve exponential and logarithmic equations. For those that cannot be solved analytically, use graphical methods to find approximate solutions. |  |  |  |  |  |
|  | P2.4 | Solve exponential and logarithmic equations when possible. For those that cannot be solved analytically, use graphical methods to find approximate solution. |  |  |  |  |  |
|  | P6.2 | Graph transformations of the sine and cosine functions (involving changes in amplitude, period, midline and phase changes) and explain the relationship between constraints in the formula and transformed graph. | X |  |  |  |  |
|  | Sec 7.7 | Graph transformations of tangent functions | X |  |  |  |  |
|  | P6.6 | Prove trigonometric identities and derive some of the basic ones. Know the fundamental identities. | X |  |  |  | Robotics 101 |
|  | P6.7 | Find a sinusoidal function to model a given data set or situation and explain how the parameters of the model relate to the data set or situation. | X |  |  |  |  |

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| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Analytic Trigonometry Chapter 8 | P6.3 | Know the basic properties of the inverse trigonometric functions: $\sin ^{-1} x, \cos ^{-1} x, \tan ^{-1} x$, including their domains and ranges. Recognize their graphs. |  |  |  |  |  |
|  | P6.4 | Know basic trigonometric identities for sine cosine and tangent ( Fundamental, sum and difference, co functions, double and half angle formulas) | X |  |  |  | Robotics 101 |
|  | P6.5 | Solve trigonometric equation using basic identities and inverse trigonometric functions | X |  |  |  | Robotics 101 |
|  | CCSS | Prove the addition and subtraction formula for sine, cosine, and tangent and use them to solve problems. | X |  |  |  | Robotics 101 |
|  | P6.6 | Prove trigonometric identities and derive some of the basic ones (double angle formulas from sum and difference formulas, half angles formula from double angle formula) |  |  |  |  |  |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Miscellaneous | Application of Trigonometric Functions | Real world applications of problems involving trigonometry such as the laws of sine and cosine. |  |  |  |  | Robotics 101 |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Polar Coordinates Chapter 10 | P9.1 | Convert between polar and rectangular coordinates. Graph functions given in polar coordinates |  |  |  |  |  |
|  | P9.2 | Write complex numbers in polar form. Know and use De Moivre's Theorem |  |  |  |  |  |
|  | P9.3 | Evaluate parametric equations for given values of parameter |  |  |  |  |  |
|  | P9.4 | Convert between parametric and rectangular forms of equations |  |  |  |  |  |

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| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Polar Coordinates Chapter 10 | P9.5 | Graph curves described by parametric equation and find parametric equations for a given graph |  |  |  |  |  |
|  | P9.6 | Use parametric equations in applied contexts to model situations and solve problems |  |  |  |  |  |
|  | CCSS | Represent complex numbers on the complex plane in rectangular and polar form (including real and imaginary numbers), and explain why the rectangular and polar forms of a given complex number represent the same number. |  |  |  |  |  |
| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Vectors, Matrices, and Systems of Equations Chapter 12 | P7.1 | Perform operations (addition, subtraction, and multiplication by scalars) on vectors in the plane. Solve applied problems using vectors. |  |  |  |  |  |
|  | P7.2 | Know and apply the algebraic and geometric definitions of the dot product using vectors |  |  |  |  |  |
|  | P7.3 | Know the definitions of matrix addition and multiplication. Add, subtract, and multiply matrices. Multiply a vector by a matrix. |  |  |  |  |  |
|  | P7.5 | Define the inverse of a matrix and compute the inverse of two-by-two and three-by-three matrices when they exist |  |  |  |  |  |
|  | P7.6 | Explain the role of determinants in solving systems of linear equation using matrices and compute determinants of two-by-two and three-by-three matrices. Use Crammer's Rule |  |  |  |  |  |
|  | P7.7 | Write systems of two and three equations in matrix form. Solve such systems using Gaussian elimination or inverse matrices. |  |  |  |  |  |
|  | P7.8 | Represent and solve systems of inequalities in two variable and apply these methods in linear programming situations to solve problems |  |  |  |  |  |
|  | Misc. | Solve $2 \times 2$ and $3 \times 3$ systems using row operations (rref), substitution, and by elimination. Be able to solve with and without a calculator. |  |  |  |  |  |

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| Purpose and Vision |  | Understanding and Applying Pre-Calculus and Trigonometry |  | $\begin{aligned} & \text { 品 } \\ & \frac{0}{c} \\ & \frac{0}{3} \\ & 0 \\ & \underline{c} \end{aligned}$ | $\begin{aligned} & 3 \\ & 0 \\ & \text { o } \\ & \frac{1}{3} \\ & 0 \\ & \underline{y} \end{aligned}$ | 틍 $\frac{0}{6}$ $\frac{9}{3}$ | 으 <br> 유 <br> ¢ <br> 0 |
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| Unit | Standard | Capacity Breakdown |  |  |  |  |  |
| Sequences, Series and Math Induction Chapter 13 | P8.1 | Know, explain and use sigma and factorial notation |  |  |  |  |  |
|  | P8.2 | Given arithmetic, geometric, or recursively defined sequence, write an expression for the nth term when possible. Write a particular term of a sequence when given the nth term. |  |  |  |  |  |
|  | P8.3 | Understand, explain and use the formulas for the sums of finite arithmetic and geometric sequences |  |  |  |  |  |
|  | P8.4 | Compute the sums of infinite geometric series. Understand and apply the convergence criterion for geometric series. |  |  |  |  |  |
|  | P8.5 | Understand and explain the principle of mathematical induction and prove statements using mathematical induction |  |  |  |  |  |
|  | P8.6 | Prove the binomial theorem using mathematical induction. Show its relationship to Pascal's Triangle and to combinations. Use the binomial theorem to find terms in the expansion of a binomial to a power greater than 3 . |  |  |  |  |  |
| Analytical Geometry Chapter 11 | P9.7 | Know, explain, and apply the locus definitions of parabolas, ellipses and hyperbolas and recognize conic sections in applied situations |  |  |  |  |  |
|  | P9.8 | Identify parabolas, ellipses and hyperbolas from equations, write the equations in standard form, and sketch an appropriate graph of the conic section |  |  |  |  |  |
|  | P9.9 | Derive equation for a conic section from given geometric information. Identify key characteristics of a conic section form its equation or graph. |  |  |  |  |  |
|  | P9.10 | Identify conic sections whose equations are in polar or parametric form. |  |  |  |  |  |

